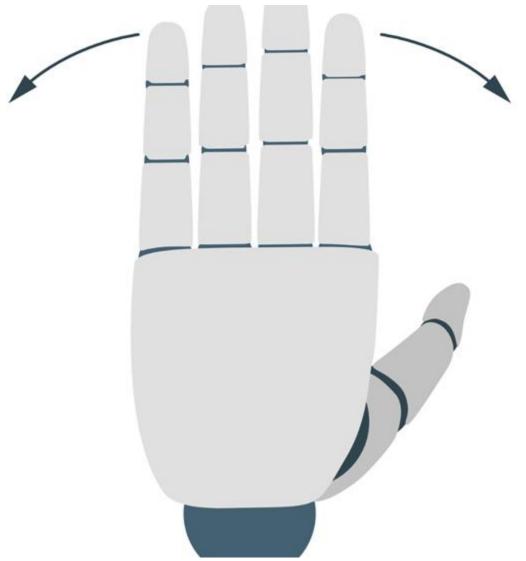




# Workshop Unit 7 Sensor Integration

TA Habib Ben Abda

08.10.2025

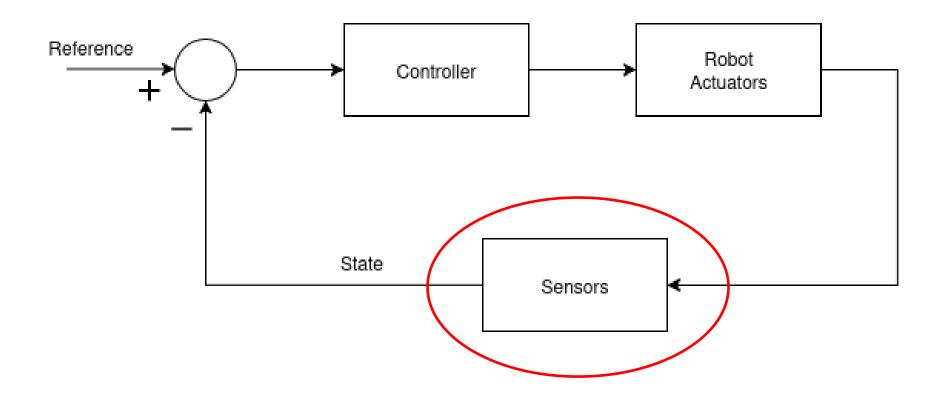




# **Closed Loop Controller**



Robot = Sensors + Actuators

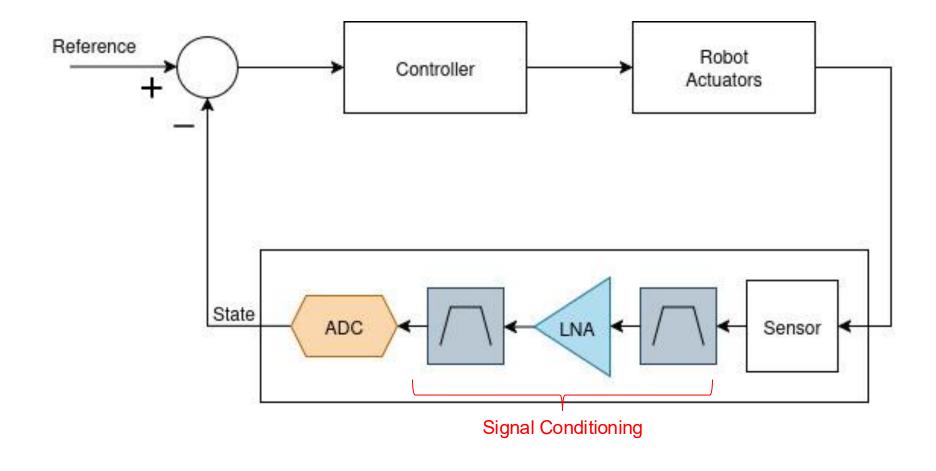






# **Closed Loop Controller**



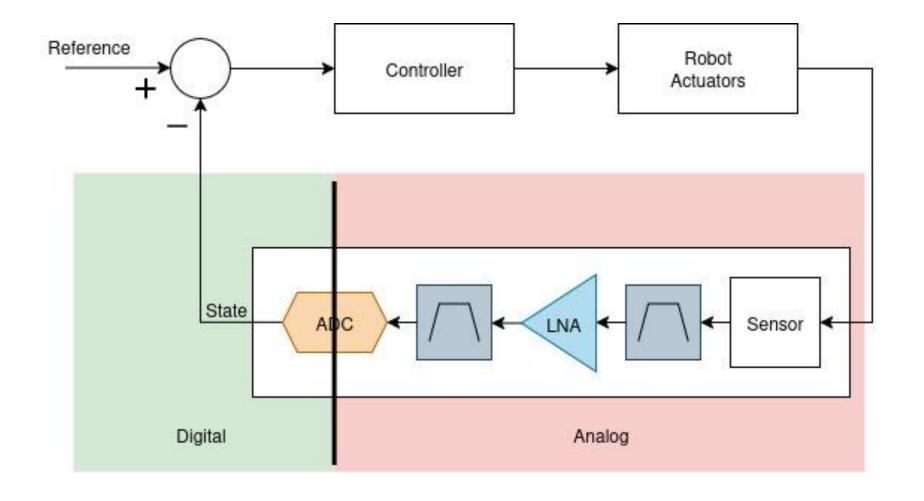






# **Closed Loop Controller**





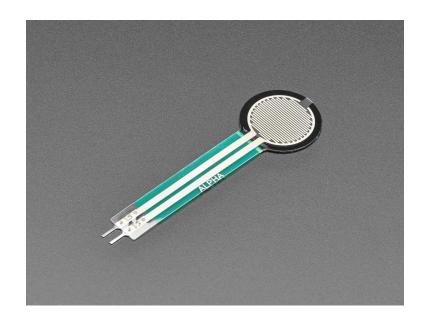




# DIY sensors VS. Off-the-shelf sensor











#### Sensor VS. Sensor module



#### Example:



#### **BMP390**

Digital pressure sensor







#### Sensor VS. Sensor module



#### 6.3. Connection diagram I<sup>2</sup>C

#### Example:

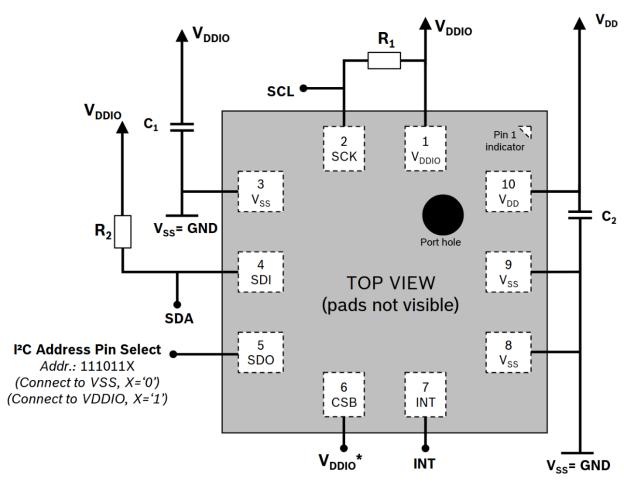


Figure 25: I<sup>2</sup>C connection diagram (Pin1 marking indicated)



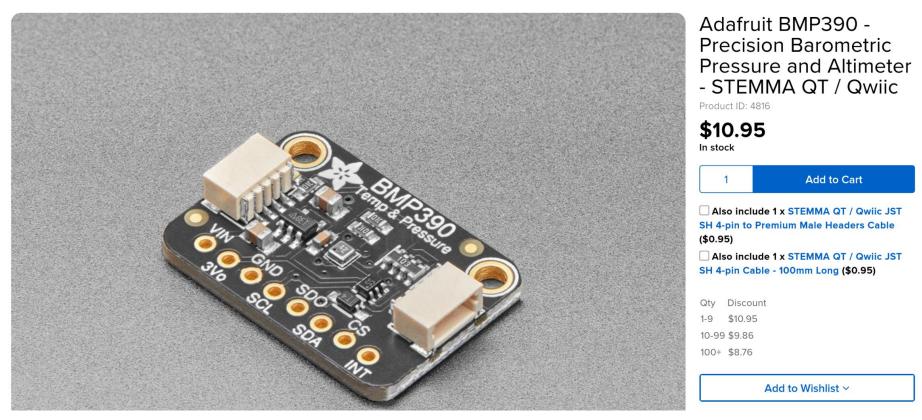


#### Sensor VS. Sensor module



#### Example:









# **Analog to Digital Converters (ADC)**



#### 1. Resolution

- Number of bits (12-bit → 4096 levels)
- Effective number of bits (ENOB)
- Inversely proportional to sampling rate

#### 2. Sampling rate

• Nyquist:  $fs = 2 \times fN$ 



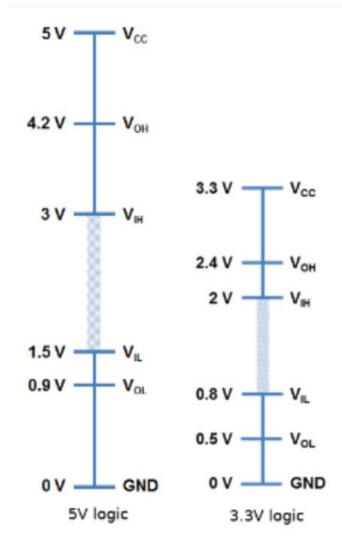


# Signal Range



#### Signals are usually encoded as voltage:

- All the voltages are referenced to a common potential (usually denoted as ground, GND)
- Commonly used 5V, 3.3V, 1.8V systems





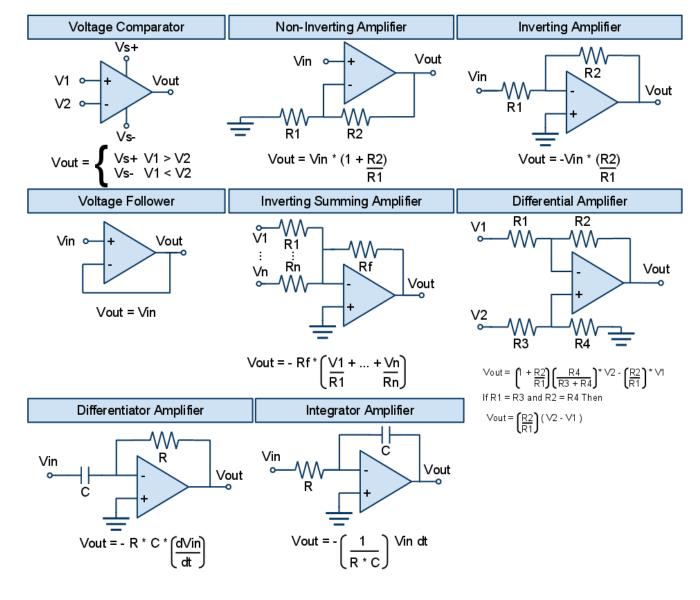




# **Amplifiers**

## **Basic Operational Amplifier Configurations**











# FSR® 400 Series Data Sheet

Force Sensing Resistors®

#### **Features and Benefits**

- Actuation force as low as 0.2N and sensitivity range to 20N
- Cost effective
- Ultra thin
- Robust; up to 10M actuations
- · Simple and easy to integrate

#### Description

Interlink Electronics FSR® 400 Series is part of the single zone Force Sensing Resistor® family. Force Sensing Resistors, or FSR's, are robust polymer thick film (PTF) devices that exhibit a decrease in resistance with increase in force applied to the surface of the sensor. This force sensitivity is optimized for use in human machine interface devices including automotive electronics, medical systems, industrial controls and robotics.

The FSR 400 Series sensors come in seven different models with four different connecting options. A battery operated demo is available. Call us for more information at +1 805-484-8855.



FSR® 400 Short 5mm Circle x 20mm



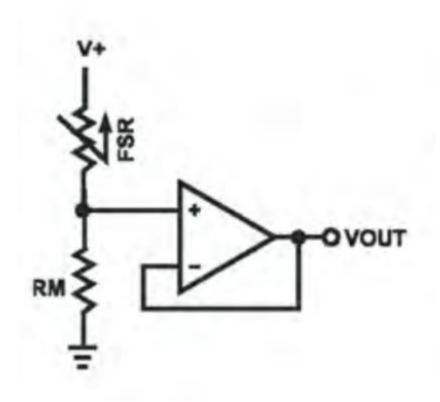
FSR® 400 5mm Circle x 38mm





# Voltage divider





$$V_{OUT} = \frac{R_M V +}{\left(R_M + R_{FSR}\right)}$$





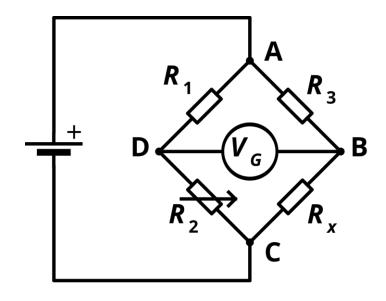
# Wheatstone Bridge



- Measures small resistance changes as differential voltage → cancels noise and drift.
- Reduces **effects of supply variation**.
- High sensitivity when bridge is near balance.

At balance (VG = 0):

$$\frac{R1}{R2} = \frac{R3}{Rx}$$







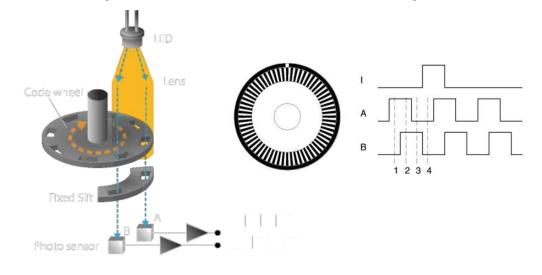
#### Relative measurement & Absolute measurement



## Challenges with absolute measure:

- Requires high calibration accuracy
- Requires stable references
- Sensitive to drift, noise, and environmental variations
- Achieving long-term stability is expensive and complex

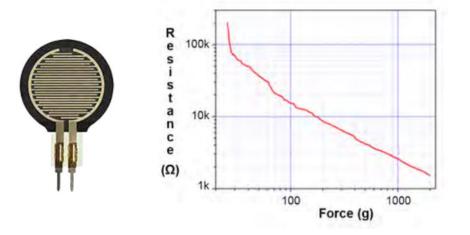
## Linear system vs Non-linear system



Rotary Encoder





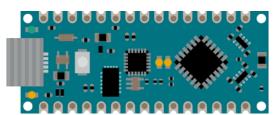


Force Sensitive Resistor

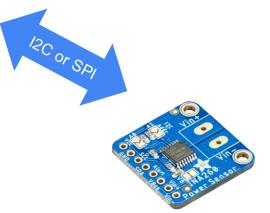
# **Potential Setup**















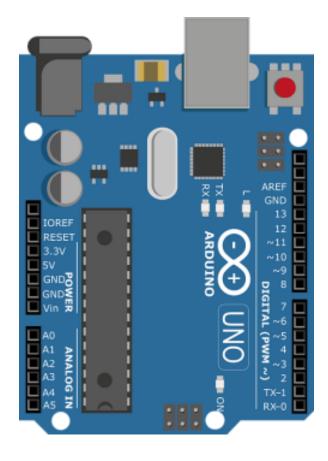
# Why use a µC board?



- GPIO: analog and digital
- I2C, SPI
- UART
- PWM
- Voltage Supply & Ground

#### Additional modules:

- SD card
- BLE
- Sensors
- ...



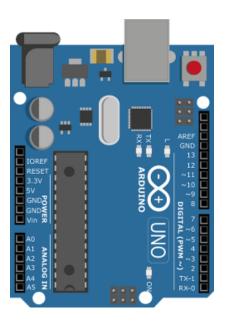




# Arduino-style embedded programming



```
#include <Arduino.h>
void setup() {
    Serial.begin(9600);
void loop() {
    Serial.println( "Hello world!" );
   delay( 500 );
```

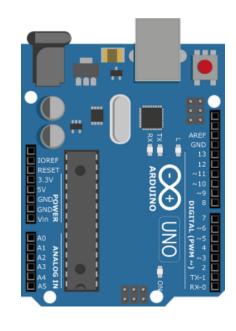






# Boards









Teensy



STM32



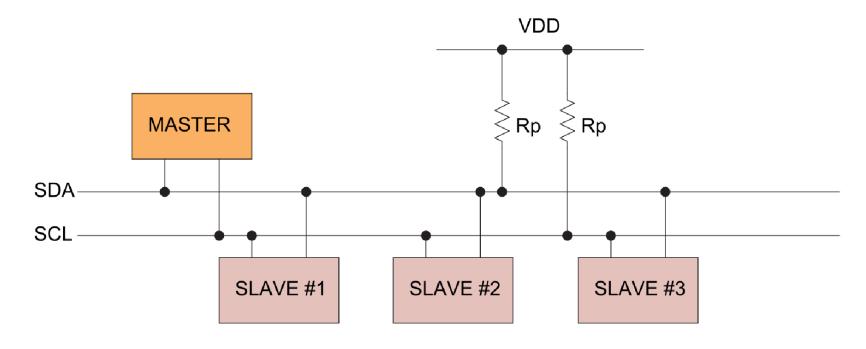


## I2C



#### 2 wire serial bus

#### Unique address for each device



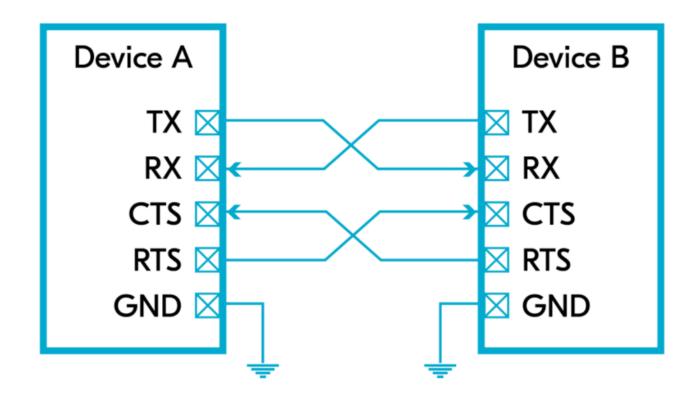




#### **UART**



Data streaming set by baud rate: 9600, 57600, 115200, 921600



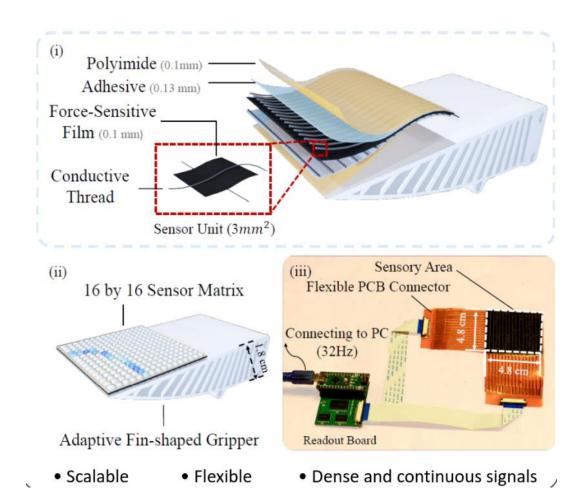
UART connection with hardware flow control

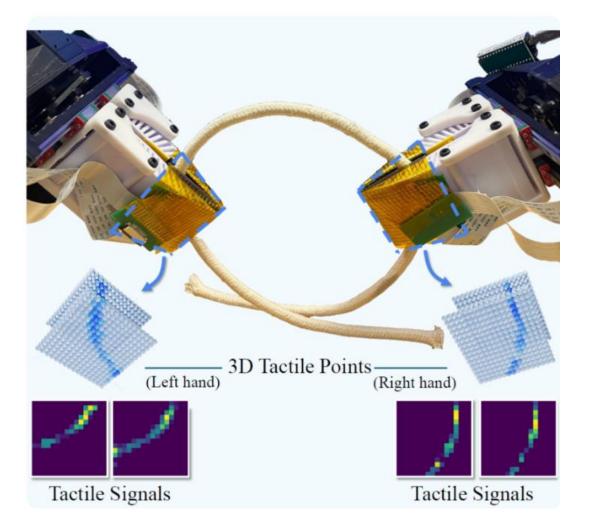




# Example by Binghao Huang











#### Finite number of channels



- Limited number of ADC channels
- Communication bottleneck
- Cross talk

#### Typical solutions:

- Multiplexing
- Bus sharing
- Multithreading
- System partitioning

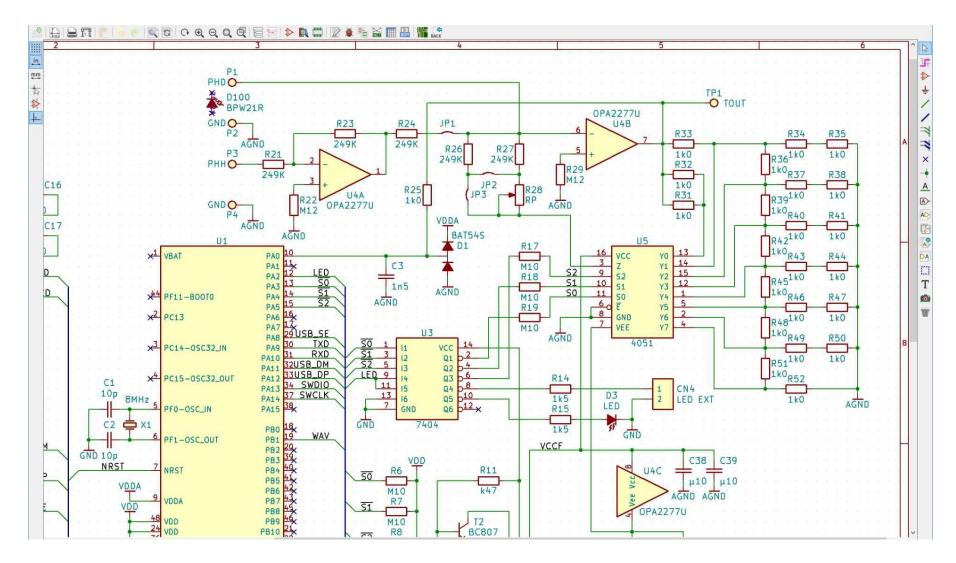








Step 1: Schematic

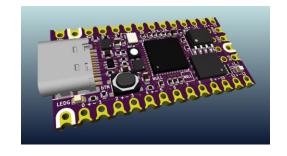


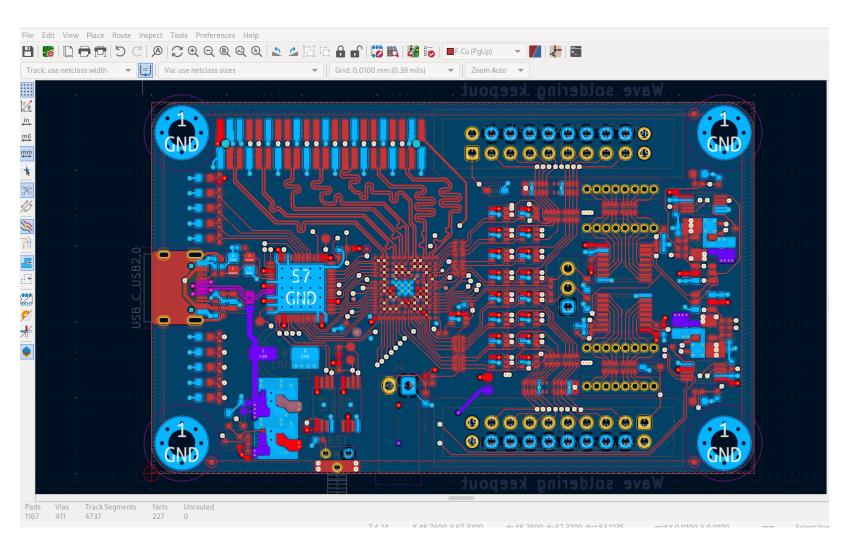






Step 2: Layout











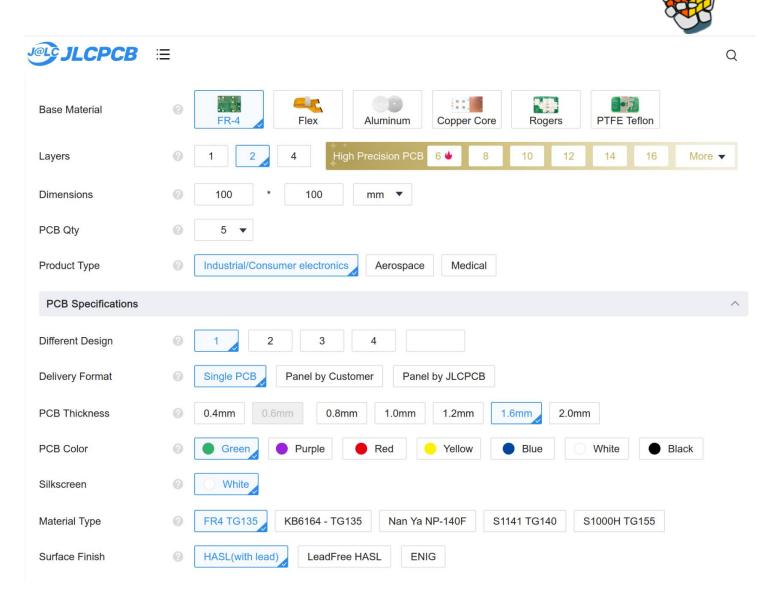
Step 3: generate **Gerber files** (equivalent to .stl in CAD)







Step 4: Order PCB from manufacturer







https://jlcpcb.com/

# **ETH** zürich



